

2056
M.E. (Mechanical Engineering)
Second Semester
MME-201: Continuum Mechanics

Time allowed: 3 Hours

Max. Marks: 50

NOTE: Attempt five questions in all, selecting atleast two questions from each Part. Use usual notations and symbols for derivations. Assume suitably missing data if any. All questions carry equal marks

x-x-x

Part A

Question 1 Two tensors **A** and **B** are given in the form of their matrix representations

$$[A] = \begin{bmatrix} \cos(\theta) & \sin(\theta) & 0 \\ -\sin(\theta) & \cos(\theta) & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad [B] = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

Verify that these matrices are orthogonal. Show that $[A]$ describes a rotation and $[B]$ a reflection. Give a geometrical interpretation.

Question 2 Apply the operator ∇ to products of smooth vector fields u and v to establish the following identity

$$\nabla \cdot (u \times v) = v \cdot \nabla \times u - u \cdot \nabla \times v$$

Question 3 In a deformation of a three-dimensional problem, the displacement components of u are found to be

$$u_1 = x_1 - \frac{1}{4}x_2, \quad u_2 = x_1 + 2x_2, \quad u_3 = -3x_3$$

Compute the matrix representation of F^{-1} and F and deduce that the deformation is *isochoric*.

Question 4 A body undergoes uniform extension in all three directions according to

$$x_1 = \lambda_1 X_1, \quad x_2 = \lambda_2 X_2, \quad x_3 = \lambda_3 X_3.$$

Find the matrix representations of the tensors F , R , U , E , and e .

P.T.O.

(2)

Part B

Question 5 At a certain point of a body the component of the *Cauchy* stress tensor are given by

$$[\sigma] = \begin{bmatrix} 5x_2x_3 & 3x_2^2 & 0 \\ 3x_2^2 & 0 & -x_1 \\ 0 & -x_1 & 0 \end{bmatrix} \frac{kN}{cm^2}.$$

Find the components of the *Cauchy* traction vector $\mathbf{t}$ at the point on the plane whose normal has direction ratios 3 : 1 : -2. Find the normal and shear components of $\mathbf{t}$ on that plane.

Question 6 The motion of a continuum body is given in the form

$$\mathbf{x} = (1 + \alpha(t)t)\mathbf{X},$$

with the scalar function $\alpha(t)$ and the set $\{\mathbf{e}_a\}$, $a = 1, 2, 3$ of orthogonal unit vectors. Find the expression for the spatial mass density ρ in terms of ρ_o so that the continuity equation is satisfied.

Question 7 Starting from the global form of the second law of thermodynamics, show that the local spatial form of the second law is

$$\frac{\partial \eta}{\partial t} \geq -\nabla \cdot (\mathbf{h} + \eta \mathbf{v}) + r$$

Question 8 In the context of *Objectivity*, What is a *Euclidean transformation*? When is a spatial vector field said to be *objective*? Show that the spatial velocity field is *not* objective. Similarly determine the transformation for the spatial acceleration field and identify the quantities that correspond to the *Euler acceleration*, *centrifugal acceleration*, and *Coriolis acceleration*. Is the acceleration field objective?

x-x-x