

2122
M.E. (Mechanical Engineering)
Third Semester
MME-302(e): Optimization Techniques

Time allowed: 3 Hours

Max. Marks: 50

NOTE: Attempt five questions in all, selecting atleast two questions from each Part.

x-x-x

PART-A

1.	a) Why do some problems have multiple optimal feasible solutions? How such information is useful for decision making ? Explain. b) Explain the following concept in the context of liners programming: i) Convex polygon . ii) Redundant constraints .	5 5																														
2.	a) Define the gradient of the function. Explain its importance in the multi variable optimization. b) Using the variable metric method, find the minimum of the function Min $f(X) = x_1^2 - x_1x_2 + 3x_2^2$. Take initial point as [1,2].	10																														
3.	Solve the following program by use of the Kuhn-Tucker conditions: minimize: $Z = x_1^2 + 5x_2^2 + 10x_3^2 - 4x_1x_2 + 6x_1x_3 - 12x_2x_3 - 2x_1 + 10x_2 + 5x_3$ subject to: $x_1 + 2x_2 + x_3 \geq 4$ with: all variables non negative.	10																														
4.	Find the optimal cost of the following transportation model: <table style="margin-left: auto; margin-right: auto;"> <tr> <td></td> <td>D1</td> <td>D2</td> <td>D3</td> <td>D4</td> <td>Supply</td> </tr> <tr> <td>O1</td> <td>12</td> <td>18</td> <td>13</td> <td>20</td> <td>50</td> </tr> <tr> <td>O2</td> <td>17</td> <td>11</td> <td>16</td> <td>15</td> <td>60</td> </tr> <tr> <td>O3</td> <td>11</td> <td>10</td> <td>14</td> <td>13</td> <td>40</td> </tr> <tr> <td>Demand</td> <td>20</td> <td>25</td> <td>10</td> <td>35</td> <td></td> </tr> </table>		D1	D2	D3	D4	Supply	O1	12	18	13	20	50	O2	17	11	16	15	60	O3	11	10	14	13	40	Demand	20	25	10	35		10
	D1	D2	D3	D4	Supply																											
O1	12	18	13	20	50																											
O2	17	11	16	15	60																											
O3	11	10	14	13	40																											
Demand	20	25	10	35																												
PART-B																																
5.	Employing graphical method, minimize the distance of the origin from the concave region bounded by the constraint : $x_1 + x_2 \geq 4$ $2x_1 + x_2 \geq 5$ $x_1, x_2 \geq 0$ Verify that the Kuhn-Tucker necessary conditions hold at the point of minimum distance.	10																														

(2)

6.	Find the optimum solution of the following constrained multivariable problem: Minimize $Z = x_1^2 + (x_2 + 1)^2 + (x_3 - 1)^2$ Subject to $x_1 + 5x_2 - 3x_3 = 6$.	10
7.	Explain application of optimization in design and analysis of springs and gears.	10
8.	<p>a) Compute the mutation and crossover in a genetic algorithm with real numbers. Explain in detail.</p> <p>b) One of management's goals in a goal programming problem is expressed algebraically as, $3x_1 + 4x_2 + 2x_3 = 60$, where 60 is the specific numeric goal and the left-hand side gives the level achieved toward meeting this goal.</p> <p>(i) Letting y_+ be the amount by which the level achieved exceeds this goal (if any) and y_- the amount under the goal (if any), show how this goal would be expressed as an equality constraint when reformulating the problem as a linear programming model.</p> <p>(ii) If each unit over the goal is considered twice as serious as each unit under the goal, what is the relationship between the coefficients of y_+ and y_- in the objective function being minimized in this linear programming model?</p>	3 7