Exam. Code: 0927 Sub. Code: 6571

## 2122

## B.E. (Electronics and Communication Engineering) Third Semester MATHS-301: Linear Algebra and Complex Analysis

Time allowed: 3 Hours Max. Marks: 50

**NOTE**: Attempt <u>five</u> questions in all, including Question No. I which is compulsory and selecting two questions from each Section. All questions carry equal marks.

- 1 (a) What is the difference between linearly independent and dependent vectors. Prove that the vectors u = (1, 2, -3), v = (1, -3, 2) and w = (2, -1, 5) of  $\mathbb{R}^3(\mathbb{R})$  is linearly independent.
- (b) Define linear transformation. Find a linear transformation  $T: \mathbb{R}^2 \to \mathbb{R}^2$  such that T(1,0) = (1,1) and T(0,1) = (-1,2).
- (c) If  $\lambda$  is an eigen value of square matrix A, then prove that  $\lambda^2$  is an eigen value of  $A^2$ .
- (d) Can the residue at a singularity be zero? Can the residue at a simple pole be zero? Justify.
- (e) What is a linear fractional transformation? What can you do with it? List special cases.

 $(5 \times 2 = 10)$ 

## Section -A

- 2 (a) Show that the set  $V = \{a + b\sqrt{2} + c\sqrt[3]{3} : a, b, c \in \mathbb{Q}\}$  form a vector space over the field  $\mathbb{Q}$  under usual addition and multiplication of real numbers.
- (b) Find a basis and dimension of the solution space

$$\begin{cases} x + 2y + 4z + s = 0, \\ 2x + y + 5z - 2s + 2t = 0, \\ x - y + z + s + 6t = 0. \end{cases}$$

- 3 (a) Let the linear transformation  $T: \mathbb{R}^3 \to \mathbb{R}^3$  be defined as T(x, y, z) = (2x, 4x y, 2x + 3y z). Verify Rank Nullity theorem for T.
  - (b) If  $B_1 = \{(1, 0), (0, 1)\}$  and  $B_2 = \{(1, 2), (2, 3)\}$  are basis of  $\mathbb{R}^2$ , then find the transition matrices P and Q from basis  $B_1$  to  $B_2$  and  $B_2$  to  $B_1$  respectively. Also verify that  $Q = P^{-1}$ .
  - 4 (a) Prove that a linear transformation  $T: V \to W$  is non-singular if and only if set of images of a linearly independent set is linearly independent.

(b) State Cayley–Hamilton theorem along with its applications. Verify the same for the matrix  $A = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 2 & 0 \\ 2 & -1 & 0 \end{bmatrix}$ . Hence find  $A^{-1}$ .

## Section-B

- 5 (a) If f(z) is differentiable at  $z_0$ , then show that f(z) is continuous at  $z_0$ .
- (b) Find u and v so that  $f(z) = \frac{z-i}{z+i}$  is of form f(z) = u(x,y) + iv(x,y). Determine all points (if any) at which the Cauchy-Riemann equations are satisfied and determine all points at which the function is differentiable.
- (c) Solve:  $\sin z = 100$ .
- 6 (a) Find the Laurent series expansion for  $f(z) = \frac{7z-2}{z^3-z^2-2z}$  in the regions given by (i) 1 < |z+1| < 3, (ii) |z+1| > 3.
- (b) Evaluate the integral  $I = \int_0^{2\pi} \frac{1+\sin\theta}{3+\cos\theta} d\theta$ .
- 7(a) Show that the mapping w = 1/z maps every straight line to a circle or a straight line, and every circle to a circle or straight line. Give an example of a circle that maps to a line, and a line that maps to a circle.
- (b) Write a note on different types of singularities with suitable examples. Find all the singularities of the function  $f(z) = e^{1/(1-z)}$  in the finite plane and the corresponding residues.