

1079
B.E. (Electronics and Communication Engineering)
Third Semester
EC-302: Signal and Systems

Time allowed: 3 Hours

Max. Marks: 50

NOTE: Attempt five questions in all, including Question No. 1 which is compulsory and selecting two questions from each Section.

x-x-x

1. (a) Describe representation of Mechanical and Hydraulic systems as differential equations.
- (b) For the following impulse response, determine, whether the system is causal, and stable: $h(t) = \{e^{-2t}u(t-1)\}$
- (c) Determine the Laplace transform of the signal:
 $x(t) = (1 + 0.5 \sin(t)) \sin(1000t) u(t)$
- (d) Find the final value of the signal corresponding to the following Z-transform
$$X(z) = \frac{1 + z^{-1}}{1 - 0.25z^{-2}}$$
- (e) Specify the Nyquist rate and Nyquist interval for the signal:
 $x(t) = \text{sinc}(250t) + \text{sinc}^2(200t)$

(5 × 2 = 10)

Section-A

2. (a) Find whether the following systems are Memoryless, Time-invariant, Linear, Causal, and Stable. Justify your answer. (5)
 - i. $y(t) = x(t-2) + x(2-t)$
 - ii. $y[n] = \cos(2\pi x[n+1]) + x[n]$
- (b) The unit impulse response of an LTI system is $h(t) = e^{-t}u(t)$. Find the system's zero state response $y(t)$ if the input signal is $x(t) = e^{-2t}u(t-3)$. (5)
3. (a) Consider the electric circuit shown in Fig 1: (5)
 - i. Determine the differential equation that relates the input current $x(t)$ to output current $y(t)$.
 - ii. Determine the zero-input response given initial conductor currents of 1A each. That is, find $y_0(t)$, given $i_{L1}(0) = i_{L2}(0) = 1A$.

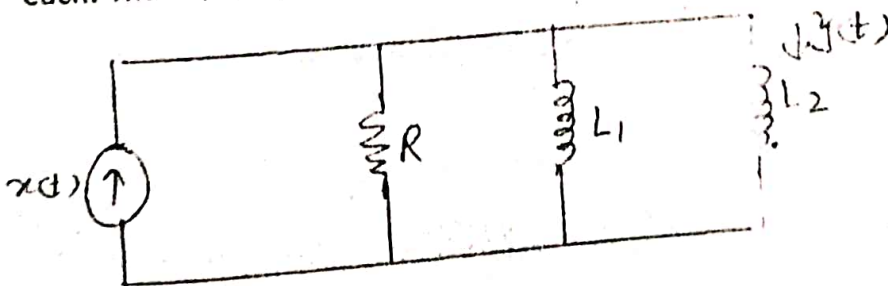


Fig 1.

(b) Find the Fourier transform of the signal: (5)

$$x(t) = t \cdot e^{-at} u(t)$$

4. (a) Determine the periodic signal $x(n)$ with period $N=8$, whose DTFS coefficients are as follows: (5)

$$X_k = \cos \frac{k\pi}{4} + \sin \frac{3k\pi}{4}$$

(b) Determine the unit impulse response $h[n]$ of the system: (5)

$$y[n] - 6y[n-1] + 25y[n-2] = 2x[n] - 4x[n-1]$$

Section-B

5. (a) Find the DTFT of the sequence (5)

$$x(n) = \frac{1}{4} \text{Sinc}\left(\frac{1}{4}(n-2)\right)$$

(b) Solve, by using Laplace Transform, the following set of simultaneous differential equations: (5)

$$2 \frac{dx(t)}{dt} + 4x(t) + \frac{dy(t)}{dt} + 7y(t) = 5u(t)$$

$$\frac{dx(t)}{dt} + x(t) + \frac{dy(t)}{dt} + 3y(t) = 5\delta(t)$$

The initial conditions are $x(0^-) = y(0^-) = 0$.

6. (a) Determine the signal $x(n)$ whose z-transform is given by (5)

$$X(z) = \log(1 + az^{-1}), \quad |z| > |a|$$

(b) Determine the Z-transform of the signal and sketch the ROC: (5)

$$x[n] = n \left(\frac{1}{2}\right)^{|n|}$$

7. (a) Describe the reconstruction of signals using Interpolation. What is Aliasing and how can it be avoided in the sampled signals? (5)

(b) Determine the state-space representation of the system (5)

$$H(s) = \frac{3s + 7}{(s+1)(s+2)(s+5)}$$