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Exam.Code: 0919 Sub. Code: 6802

## 1128

## B.E. (Computer Science and Engineering) Seventh Semester CS-701: Digital Image Processing

Time allowed: 3 Hours

Max. Marks: 50

**NOTE**: Attempt <u>five</u> questions in all, including Question No. I which is compulsory and selecting two questions from each Unit.

x-x-x

- I. Attempt the following:
  - a) Where you need non-uniform sampling and quantization?
  - b) Define false contouring.
  - c) What is Fourier transform? How is it useful in image processing?
  - d) Name the different types of derivative filters used in image processing?
  - e) Give any three applications in our daily life, which could use image segmentation.
  - f) Define shape numbers.
  - g) What is Psychovisual redundancy?
  - h) Provide the linear filter mask to find vertical edges in an image.
  - i) Discuss the need of image compression in relation to social networking.
  - i) Briefly describe the various applications of object recognition.

## UNIT-I

II. a) What do you understand by image-acquisition? Discuss the various methods of image acquisition.

b) Two images f(x,y) and g(x,y), have histograms h<sub>f</sub> and h<sub>g</sub>. Give the conditions under which you can determine the histograms of following in terms of h<sub>f</sub> and h<sub>g</sub>. Describe how to obtain these histograms.

i) f(Ay)-g(x,y)ii) f(x,y) \* g(x,y) (6,4)

- III. a) Why a digital image is subjected to spatial filtering? Discuss the limiting effect of repeatedly applying a 3x3 low pass spatial filter to a digital image. Ignore the border effects.
  - b) What is noise? Explain Weiner filtering for image restoration. (5,5)
- IV. a) Briefly explain HSI and RGB color models. Describe how HSI model could be converted to RGB model?
  - b) What is a Laplacian mask? Find the equivalent filter, H(u,v), that implements in the frequency domain the spatial operation performed by the Laplacian mask. (5,5)

P.T.O.

(10x1)

## UNIT-II

- V. a) Prove that gradient of an image by using Prewitt operator along horizontal direction can be obtained by convolving the image by [1 1 1] followed by [-1 0 1] and finally dividing the result by 3.
  - b) Explain the polygon approximations with a suitable example (5)
- VI. a) Describe about region based image segmentation methods. How are they better than thresholding methods?
  - b) Give the advantages of DWT over DCT with respect to image compression. Explain with suitable example. (5,5)
- VII. a) Explain how Fourier descriptors are used for boundary description of any digital boundary in xy plane.
  - b) Texture is an important regional descriptor and it could be found by (2,1,2) using co-occurrence matrices. Consider a binary image of size 200x200 pixels, with a vertical black band extending from columns 1 to 99 and a vertical white band extending from columns 100 to 200.

 i) Obtain the co-occurrence matrix of this image using the position operator "one pixel to the right.

ii) Normalize this matrix so that its elements become probability estimates.

iii) Compute the six texture descriptors. (5,5)

x-x-x