

1128  
M. E. (Mechanical Engineering)  
First Semester  
MME-103: Continuum Mechanics

Time allowed: 3 Hours

Max. Marks: 50

NOTE: Attempt five questions in all, selecting atleast two questions from each Part. Use usual notations and symbols for derivations. Assume suitable missing data, if any.

x-x-x

Section A

Q.1 (a) In direct notation prove that  $S(a \otimes b) = (Sa) \otimes b$ . (b) Prove that the Cartesian components of the product of two tensors  $S$  and  $T$  are  $(ST)_{ij} = S_{ik}T_{kj}$ .

Q.2 Prove in direct notation that  $\frac{d}{dA}I_2(A) = I_1(A)I - A^T$ .

Q.3 Given the motion  $x_1 = 2X_2$ ,  $x_2 = 5X_3$ ,  $x_3 = X_1$ , (a) calculate the principal stretches  $\lambda_1$ ,  $\lambda_2$ , and  $\lambda_3$  (common to both  $U$  and  $V$ ); (b) calculate the principal directions  $N_1$ ,  $N_2$ , and  $N_3$  of  $U$ ; (c) calculate the principal directions  $n_1$ ,  $n_2$ , and  $n_3$  of  $V$ ; (d) verify that the principal directions of  $U$  and  $V$  differ by a rotation, i.e.,  $n_1 = RN_1$ ,  $n_2 = RN_2$ ,  $n_3 = RN_3$ .

Q.4 In direct notation prove that  $\dot{F} = LF$ .

Section B

Q.5 Starting with the spatial statement of the balance of linear momentum in integral form.

$$\frac{d}{dt} \int_P \rho v dv = \int_P \rho b dv + \int_{\partial P} t da.$$

derive the corresponding pointwise form

$$\rho \dot{v} = \rho b + \text{div} T.$$

Q.6 What is invariance under superposed rigid body motions (SRBM)? Prove that  $t^+ = Qt$ .

Q.7 Prove in direct notation that

$$\frac{\partial \psi}{\partial F} \cdot \dot{F} = \frac{\partial \psi}{\partial F} F^T \cdot L.$$

Q.8 Demonstrate that the Newtonian (fluid) constitutive equation can be combined with conservation of linear momentum to obtain the Navier-Stokes equations.

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